

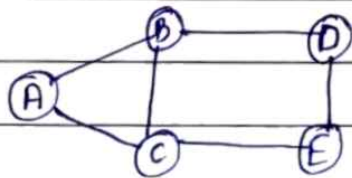
* Graph

- A graph G is a set of vertices (V) and set of edges (E).
- The set V is a finite, nonempty set of vertices. The set E is a set of pairs of vertices representing edges.

$$G = (V, E)$$

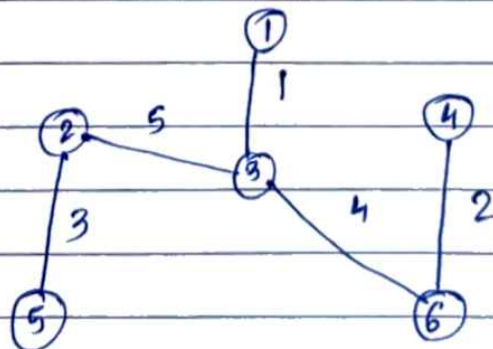
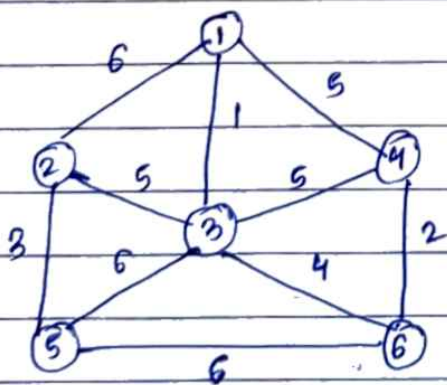
$V(G)$ = Vertices of graph G

$E(G)$ = Edges of graph G



* Minimum spanning tree

- With applications of weighted graphs, it is often necessary to find a spanning tree for which the total weight of the edges in the tree is as small as possible.
- Such a spanning tree is called a minimal spanning tree or minimum cost spanning tree.



* Prim's Algorithm:

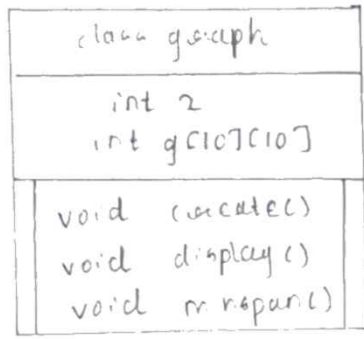
- Let the graph $G = (V, E)$ has n vertices.

Step 1: choose a vertex v_1 of G . Let $V_T = \{v_1\}$ and $E_T = \{\}$

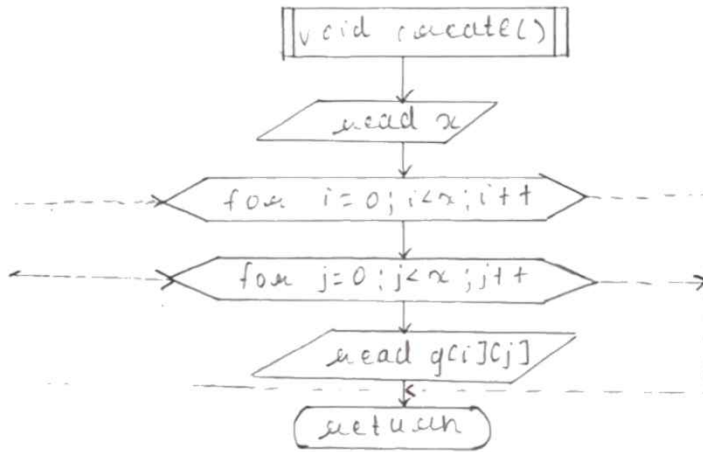
Step 2: choose a nearest neighbour v_i of v_1 that is adjacent to v_1 , $v_j \in V_T$ and for which the edge (v_i, v_j) does not form a cycle with members of E_T . Add v_i to V_T and add (v_i, v_j) to E_T .

Step 3: Repeat step 2 until $|E_T| = n-1$. Then V_T contains all n vertices of G and E_T contains the edges of the minimum cost spanning tree of G .

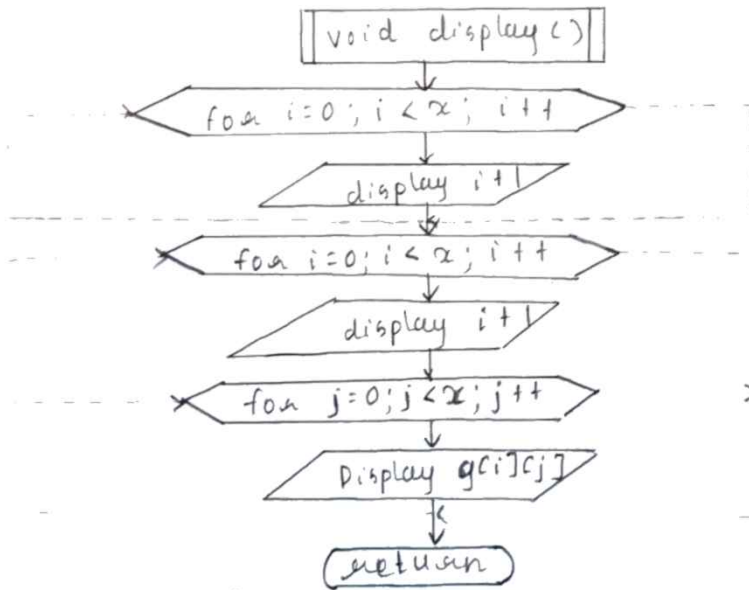
Flowchart for class graph



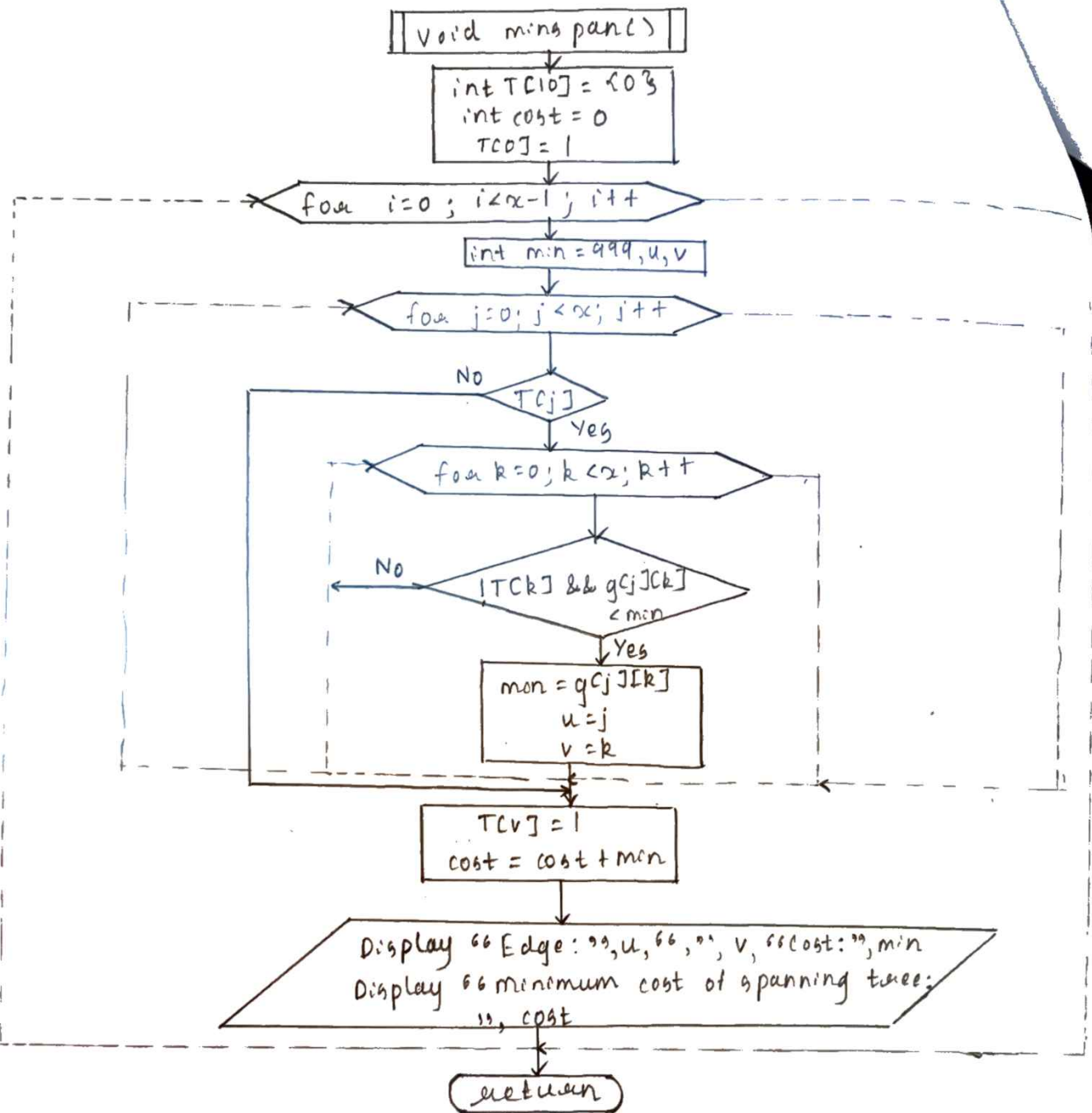
→ Flowchart for void create()



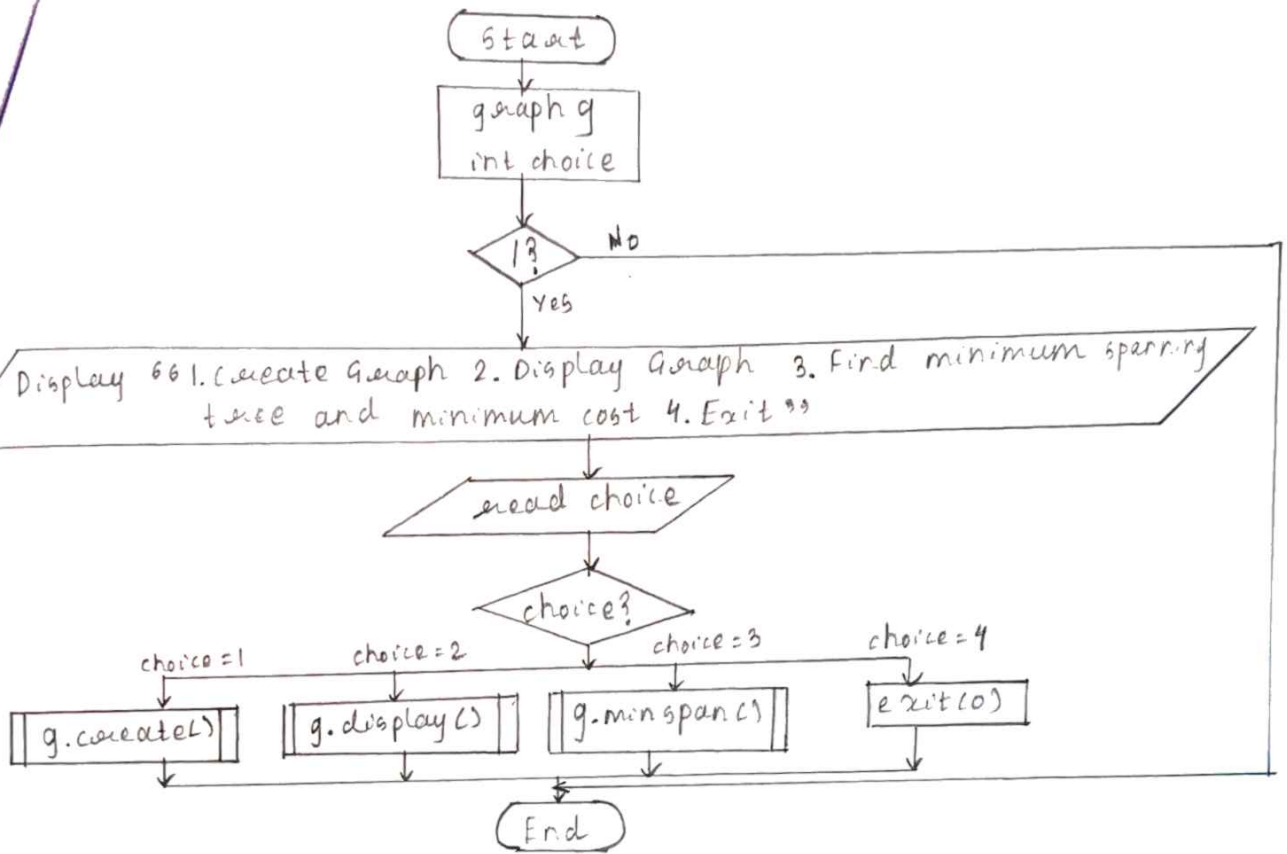
→ flowchart for void display()



→ Flowchart for void minspan()



switch case for int main()



→ Pseudocode for class graph

1. Declare int x

int g[10][10]

2. Declare function create()

function display()

function minspan()

~~3.~~

→ Pseudocode for ~~class~~ void create()

1. Display "Enter number of nodes: "

2. read x

3. for i=0; i<x; i++ do

begin

for j=0; j<x; j++ do

begin

Display "Enter cost of graph: "

read g[i][j]

end

end

4. return

→ Pseudocode for void display()

1. for i=0; i<x; i++ do

begin

display i+1

end

2. for i=0; i<x; i++ do

begin

display i+1

for j=0; j<x; j++ do

begin

display g[i][j]

end

end

3. return

→ Pseudocode for void minSpanc()

1. declare int T[C][0] = 0's

2. initialize cost = 0

3. initialize T[C][1] = 1

4. for $i=0; i < x-1; i++$ do

begin

 initialize $min = 999, u, v$

 for $j=0; j < x; j++$ do

 begin

 if T[C][j] then

 for $k=0; k < x; k++$ do

 begin

 if !T[C][k] and $g[C][j][k] < min$ then

 initialize $min = g[C][j][k]$

$u = j$

$v = k$

 end

 end

 initialize T[C][v] = 1

 cost = cost + min

 Display "Edge: [", u, ", ", v, "]" cost: ", min

 Display "Minimum cost of spanning tree: ", cost

end

5. return

→ Pseudocode for int mainc()

1. start

2. create object g

3. declare int choice

4. while (1) do

begin

Display "1. Create Graph 2. Display Graph 3. Find
minimum spanning tree and minimum
cost 4. Exit"

read choice

switch (choice)

case 1:

call function g.create()

break

case 2:

call function g.display()

break

case 3:

call function g.minspan()

break

case 4:

exit()

break

default:

Display "Enter valid choice"

break

end

5 End

Q1. Suppose we have an undirected graph with weights that can be either positive or negative. Do Prim's and Kruskal's algorithm produce an MST for such a graph?

Ans. Yes, negative edge weights are no problem for Prim's and Kruskal's algorithm.

- Both of these algorithms are 'greedy' algorithms and the reason why the greedy approaches to finding the MST work is that you can always get a better ST if there is an unused edge that has a lower weight than any edge on the cycle that would be created by adding it on the ST.
- This principle holds for both positive and negative edge weights.

Q2. Can a graph have more than one spanning tree?

Ans. A connected graph can have more than one spanning tree.

- All spanning trees must contain the same number of vertices as of graph, and the number of edges must be equal to $|V| - 1$.
- The spanning tree must not contain any cycle.
- A spanning tree is a subgraph of a graph in which all the vertices are connected and it does not have any loops.
- Therefore, a graph can have multiple spanning trees.

Q3. State the difference between Prim's and Kruskal's algorithm.

Soln:

Kruskal's

Prim's

1. Select the shortest edge in a network.

1. Select any vertex

2. Select the next shortest edge which does not create a cycle.

2. Select the shortest edge connected to the vertex

3. If graph is created using adjacency matrix, time complexity $\rightarrow O(n^2)$

3. If graph is created using adjacency matrix, time complexity $\rightarrow O(n^2)$

4. If graph is created using wst, Time complexity $\rightarrow O(n^2) + O(E \cdot \log n) = O(n^2)$

4. If graph is created using wst, Time complexity $\rightarrow O(E \cdot \log n)$

5. Kruskal's algorithm performs better for sparse graph

5. Prim's algorithm is comparatively less efficient for a sparse graph.